

Refine Search

Your wildcard search against 10000 terms has yielded the results below.

Your result set for the last L# is incomplete.

The probable cause is use of unlimited truncation. Revise your search strategy to use limited truncation.

Search Results -

Terms	Documents
(autonomous\$ adj2 park\$) and steer\$	35

Database:

US Pro-Grant Publication Full-Text Database
 US Patents Full-Text Database
 US OCR Full-Text Database
 EPO Abstracts Database
 JPO Abstracts Database
 Derwent World Patents Index
 IBM Technical Disclosure Bulletins

10/591235

Search:

Search History

 DATE: Saturday, April 05, 2008 [Purge Queries](#) [Printable Copy](#) [Create Case](#)

Set	Name	Query	Hit Count	Set Name
side by side				result set

DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES;
OP=OR

L26	(autonomous\$ adj2 park\$) and steer\$	35	L26
L25	L22 and (autonomous\$ adj2 park\$)	22	L25
L24	L22 and (autonomous\$ near2 park\$)	24	L24
L23	L22 and (automatic\$ near2 steer\$)	2	L23
L22	(autonomous\$ near2 (park\$ and steer\$))	24	L22
L21	L10 and (autonomous\$ with park\$)	1	L21
L20	10/591235	1	L20
PARK\$.CLM. AND ((automatic\$ near2 steer\$) with control\$) and			
L19 ((automatic\$ near2 steer\$) with (STOP\$ OR cancel\$)) and (deviat\$ with (steer\$ near2 TORQUE\$)) and (maneuver\$ near2 path\$) and @ad<=20040305		0	L19

L18	L17 and ((exce\$ or over\$ or pass\$) near3 (deviat\$ or (turn\$ adj2 aside\$))) and park\$	3 L18
L17	L13 or L15 or L16	51 L17
DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR		
(5742141 5255194 4852009 5251137 5172961 5134352 5228757 4735274 5388658 5764015 4998593 5229944 4809181 4931930 5206808 3894773 5318143 5245422 4401181 4482961 5390118 5211453 5267783)![PN]	23 L16	
L15 ("6021367" "5931252")![PN]	2 L15	
DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES; OP=OR		
L14 L12	2 L14	
DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR		
L13 ("6021367" "5931252")![URPN]	26 L13	
DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; THES=ASSIGNEE; PLUR=YES; OP=OR		
L12 L11 and (701/41 701/70).ccls.	2 L12	
L11 L10 not L9	7 L11	
L10 ((automatic\$ near3 steer\$) with control\$) and (deviat\$ with (steer\$ near4 angle\$)) and ((exceed\$ or over\$ or pass\$) near3 deviat\$) and park\$	9 L10	
L9 L4 or L8	4 L9	
((automatic\$ near3 steer\$) with control\$) and ((automatic\$ near3 steer\$) with cancel\$) and (deviat\$ with (steer\$ near4 angle\$)) and ((exceed\$ or over\$ or pass\$) near3 deviat\$) and park\$	2 L8	
L7 ((automatic\$ near3 steer\$) with control\$) and ((automatic\$ near3 steer\$) with cancel\$) and (deviat\$ with (steer\$ near4 angle\$)) and ((exceed\$ or over\$ or pass\$) near3 deviat\$) and @pd<=20060613 and park\$	0 L7	
L6 ((automatic\$ near3 steer\$) with control\$) and ((automatic\$ near3 steer\$) with cancel\$) and (deviat\$ with (steer\$ near4 angle\$)) and ((exceed\$ or over\$ or pass\$) near3 deviat\$) and @ad<=20060613 and park\$	0 L6	
L5 L4 and park\$	0 L5	
L4 ((automatic\$ near2 steer\$) with control\$) and ((automatic\$ near2 steer\$) with cancel\$) and (deviat\$ with (steer\$ near2 angle\$)) and ((exceed\$ or over\$ or pass\$) near3 deviat\$) and @ad<=20060613	2 L4	
DB=PGPB; THES=ASSIGNEE; PLUR=YES; OP=OR		
L3 11/760311	1 L3	
DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR		
L2 11/760311	0 L2	
L1 7089101.PN.	1 L1	

END OF SEARCH HISTORY